Exploring the Benefits of Physical and Virtual Manipulatives in Simple Machines

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Motivation

- Previous studies comparing usefulness of physical and virtual manipulatives show mixed results
 - Some studies show added benefits of virtual manipulatives.
 Egs: Zacharia, 2005; Finkelstein *et al.*, 2005
 - Some studies show no difference between the two. Egs: Klahr, Triona, & Williams, 2007; Zacharia & Constantinou, 2008
- Previous studies have focused on limited contexts in physics, such as electric circuits & heat/temperature

Research Questions

• Is there a difference in conceptual understanding, as measured by a multiple choice test, between students who perform experiments with physical and virtual experiments?

• Are there specific concepts that are supported more by the physical or virtual manipulatives?

Context of the Studies

- Simple machines: inclined planes & pulleys
- CoMPASS (Concept-Mapped Project-based Activity Scaffolding System) curriculum
 - Brings together dynamic concept map and text, design and inquiry based activities



friction in Inclined Plane

Friction is a <u>force</u> that resists motion and makes doing <u>work</u> seem harder because more effort must be applied to complete the task. Think about using an <u>inclined plane</u> to move an object. As the object slides on the inclined plane, the surface of the object and the surface of the inclined plane rub together and create friction. If the surface of the inclined plane is really burnpy and rough, the object will go down a lot slower than if the inclined plane was smooth. When the object is smooth, there is less friction. Another way to decrease friction when using an inclined plane is to put the object in a cart with wheels. Using wheels will help you roll the object up instead of sliding it, minimizing the friction. The <u>efficiency</u> of an inclined plane depends on the amount of friction. The less the friction, the more efficient the inclined plane.

For more details on CoMPASS, see www.compassproject.net; Puntambekar

Inclined Plane Study

- Conceptual-based physics students in lab
- Used physical <u>or</u> virtual manipulatives to perform experiments
- Varied length & height <u>or</u> length & friction of inclined plane
- Answered worksheet questions and took pre- and post-tests



IP Pre- and Post-test Performance

Section	Ν	Pre-Test	Post-Test
LH Physical	29	60%	66%
LH Virtual	37	60%	78%
LF Physical	25	59%	66%
LF Physical	30	60%	66%
LF Virtual	33	57%	67%

•LH Physical and LH Virtual are statistically the same on the pre-test (p=.9878)

•LH Virtual is statistically significantly higher than LH Physical on the post-test (p=.0008)

•No statistical difference between LF groups

Questions Leading to Difference

Four questions had 20% or more difference between LH Physical and LH Virtual

Quest. #	LH Physical	LH Virtual	Context
6.2	21%	78%	Work
7	21%	49%	Work
14	3%	86%	Work/PE
15	28%	49%	Mech. Adv.
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*All deal with a frictionless environment.

IP Question 14

An object sits at the top of a frictionless ramp. How does the object's potential energy compare to the work required to move it to the top of the ramp?

Answers	Physical	Virtual
A. The object's potential energy is	0.04	00/
greater than the required work.	28%	8%
B. The objects potential energy is less		
than the required work.	69%	0%
C. The object's potential energy is		
the same as the required work	3%	86%
D. Not enough information to		
decide	0%	5%

Inclined Plane Results Summary

- Performance difference for LH students largely the result of questions about a frictionless environment
- Appears students who used physical manipulatives had difficulty extrapolating to frictionless case
- Virtual environment can create contexts which are impossible in the real world
- Of course, frictionless experiments are not realistic

- Conceptual-based physics students in lab
- Use physical <u>and</u> virtual manipulatives to perform experiments
- Varied pulley setup
- Answered worksheet questions and took pre-, mid-, and post-tests
 - Here, focus on mid-test which allows us to compare physical and virtual conditions



Pulley Pre- and Mid-test Performance

Section	Ν	Pre-Test	Mid-Test
Physical/Virtual	21	33.7%	42.7%
Physical/Virtual	24	37.8%	47.8%
Physical/Virtual	28	37.6%	51.0%
Virtual/Physical	31	34.0%	55.7%
Virtual/Physical	31	32.6%	41.5%

•No difference in average Mid-test scores: Physical- 58.1%; Virtual-59.6%
•Large difference between sections within each condition

•Do we see any questions where there is a performance difference between students using physical or virtual manipulatives?

Pulley Questions with Performance Difference

On 7 of 13 questions, more than 20% difference between physical and virtual

Question	Physical	Virtual	Торіс
1	85%	63%	Force
6.1	90%	56%	Force
6.2	29%	81%	Work
7	75%	53%	Work (calc.)
9	17%	65%	Work
11	88%	55%	Mech. Adv.
13	32%	77%	Work

•Physical outperformed virtual on 4 questions and underperformed virtual on 3 questions

Question 6.1

You use pulley A to lift a watermelon to your tree house. If you used pulley B instead to lift the same watermelon, the *effort force* needed would:



Answers	Physical	Virtual
Increase	12.6%	28%
Decrease	87.5%	55.5%
Stay the same	0.0%	16.5%
Not enough info	0.0%	0.0%

Question 6.2

You use pulley A to lift a watermelon to your tree house. If you used pulley B instead to lift the same watermelon, the *work* needed would:



Answers	Physical	Virtual
Increase	36.5%	15.1%
Decrease	36.2%	5.1%
Stay the same	28.7%	81.5%
Not enough info	1.4%	0.0%

Pulley Results Summary

- No overall difference between students who used physical or virtual manipulatives, but differences on many specific questions
- Students who used physical manipulatives performed better on effort force and mechanical advantage questions
- Students who used virtual manipulatives performed better on work questions

Conclusions & Future Work

• Conclusions:

- Inclined Plane study indicates virtual manipulatives can help students reason about frictionless environment
- Pulley study indicated physical and virtual manipulatives may better support different concepts

• Future Work:

- Can students who only use virtual manipulatives reason about friction?
- How do students perform if they use both types manipulatives?